## Geometric and probabilistic descriptions of chaotic phase space transport

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Department of Mathematics, November 9, 2011

MultisTEPS: Multiscale Transport in Virginia
Environmental \& Physiological Systems,
www.multisteps.esm.vt.edu

## Motivation: application to real data

- Many systems defined from data or large-scale simulations
- experimental measurements, observations
- e.g., from fluid dynamics, biology, social sciences
- Data-based, aperiodic, finite-time, finite resolution — in general, no fixed points, periodic orbits, or other invariant sets (or their stable and unstable manifolds) to organize phase space


## Motivation: application to real data

- Perhaps can find appropriate analogs to the objects; adapt previous results to this setting
- Try some numerical explorations; see what merit furthers study

Chaotic phase space transport via lobe dynamics
$\square$ Suppose our dynamical system is a discrete map ${ }^{1}$

$$
f: \mathcal{M} \longrightarrow \mathcal{M}
$$

e.g., $f=\phi_{t}^{t+T}$, flow map of time-periodic vector field and $\mathcal{M}$ is a differentiable, orientable, two-dimensional manifold e.g., $\mathbb{R}^{2}, S^{2}$
$\square$ To understand the transport of points under the $f$, consider invariant manifolds of unstable fixed points

- Let $p_{i}, i=1, \ldots, N_{p}$, denote saddle-type hyperbolic fixed points of $f$.


## Partition phase space into regions

$\square$ Natural way to partition phase space

- Pieces of $W^{u}\left(p_{i}\right)$ and $W^{s}\left(p_{i}\right)$ partition $\mathcal{M}$.


Unstable and stable manifolds in red and green, resp.

## Partition phase space into regions

- Intersection of unstable and stable manifolds define boundaries.



## Partition phase space into regions

- These boundaries divide the phase space into regions



## Label mobile subregions: 'atoms' of transport

- Can label mobile subregions based on their past and future whereabouts under one iterate of the map, e.g., $\left(\ldots, R_{4}, R_{4}, R_{1},\left[R_{1}\right], R_{2}, \ldots\right)$



## Lobe dynamics: transport across a boundary

$\square W^{u}\left[f^{-1}(q), q\right] \bigcup W^{s}\left[f^{-1}(q), q\right]$ forms boundary of two lobes; one in $R_{1}$, labeled $L_{1,2}(1)$, or equivalently $\left(\left[R_{1}\right], R_{2}\right)$, where $f\left(\left(\left[R_{1}\right], R_{2}\right)\right)=\left(R_{1},\left[R_{2}\right]\right)$, etc. for $L_{2,1}(1)$


## Lobe dynamics: transport across a boundary

$\square$ Under one iteration of $f$, only points in $L_{1,2}(1)$ can move from $R_{1}$ into $R_{2}$ by crossing their boundary, etc.
$\square$ The two lobes $L_{1,2}(1)$ and $L_{2,1}(1)$ are called a turnstile.


Lobe dynamics: transport across a boundary
$\square$ Essence of lobe dynamics: dynamics associated with crossing a boundary is reduced to the dynamics of turnstile lobes associated with the boundary.


## Identifying atoms of transport by itinerary

$\square$ In a complicated system, can still identify manifolds ...


Unstable and stable manifolds in red and green, resp.

## Identifying atoms of transport by itinerary

## $\square \ldots$ and lobes



Significant amount of fine, filamentary structure.

## Identifying atoms of transport by itinerary

$\square$ e.g., with three regions $\left\{R_{1}, R_{2}, R_{3}\right\}$, label lobe intersections accordingly.

- Denote the intersection $\left(R_{3},\left[R_{2}\right]\right) \bigcap\left(\left[R_{2}\right], R_{1}\right)$ by $\left(R_{3},\left[R_{2}\right], R_{1}\right)$



## Identifying atoms of transport by itinerary



Longer itineraries...

## Identifying atoms of transport by itinerary


... correspond to smaller pieces of phase space; horseshoe dynamics, etc

## Lobe dynamics intimately related to transport


$n=0$

$n=3$

$n=1$

$n=5$

$n=2$

$n=7$

## Lobe Dynamics: example

- Restricted 3-body problem: chaotic sea has unstable fixed points.



## Compute a boundary



## Transport btwn Two Regions

- The evolution of a lobe of species $S_{1}$ into $R_{2}$

Dellnitz, Junge, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Physical Review Letters

## Transport btwn Two Regions

## Species Distribution: Species $\mathrm{S}_{\mathbf{1}}$ in Region $\mathrm{R}_{\mathbf{2}}$



## Lobe dynamics: fluid example

$\square$ Fluid example: time-periodic Stokes flow
(a)

(b)

streamlines
tracer blob
Lid-driven cavity flow

- Model for microfluidic mixer
- System has parameter $\tau_{f}$, which we treat as a bifurcation parameter — critical point $\tau_{f}^{*}=1$; above and next few slides show $\tau_{f}>1$


## Lobe dynamics: fluid example

$\square$ Structure associated with saddles of Poincaré map

some invariant manifolds of saddles

## Lobe dynamics: fluid example

$\square$ Can consider transport via lobe dynamics


## Stable/unstable manifolds and lobes in fluids


material blob at $t=0$

## Stable/unstable manifolds and lobes in fluids


material blob at $t=5$

## Stable/unstable manifolds and lobes in fluids


some invariant manifolds of saddles

## Stable/unstable manifolds and lobes in fluids


material blob at $t=10$

## Stable/unstable manifolds and lobes in fluids


material blob at $t=15$

## Stable/unstable manifolds and lobes in fluids


material blob and manifolds

## Stable/unstable manifolds and lobes in fluids


material blob at $t=20$

## Stable/unstable manifolds and lobes in fluids


material blob at $t=25$

## Stable/unstable manifolds and lobes in fluids



- Saddle manifolds and lobe dynamics provide template for motion


## Stable/unstable manifolds and lobes in fluids

$\square$ Concentration variance; a measure of homogenization


- Homogenization has two exponential rates: slower one related to lobes
- Fast rate due to braiding of 'ghost rods'


## Stirring fluids with solid rods


turbulent mixing spoon in coffee
laminar mixing
3 'braiding' rods in glycerin

## Topological chaos through braiding of stirrers

$\square$ Topological chaos is 'built in' the flow due to the topology of boundary motions
$R_{N}:$ 2D fluid region with $N$ stirring 'rods'

- stirrers move on periodic orbits
- stirrers = solid objects or fluid particles
- stirrer motions generate diffeomorphism

$$
f: R_{N} \rightarrow R_{N}
$$

- stirrer trajectories generate braids in 2+ 1 dimensional space-time


## Thurston-Nielsen classification theorem

- Thurston (1988) Bull. Am. Math. Soc.
- A stirrer motion $f$ is isotopic to a stirrer motion $g$ of one of three types (i) finite order (f.o.): the $n$th iterate of $g$ is the identity (ii) pseudoAnosov (pA): $g$ has dense orbits, (iii) reducible: $g$ contains both f.o. and pA regions
- $h_{\mathrm{TN}}$ computed from 'braid word', e.g., $\sigma_{-1} \sigma_{2}$ where $\lambda \geq \lambda_{\mathrm{TN}}$



## Topological chaos in a viscous fluid experiment

finite order


## Identifying 'ghost rods': periodic points

$$
\text { tracer blob for } \tau_{f}>1
$$

- For $\tau_{f}>1$, groups of elliptic and saddle periodic points of period 3
- streamlines around groups resemble fluid motion around a solid rod $\Rightarrow$
- At $\tau_{f}=1$, points merge into parabolic points
- Below $\tau_{f}<1$, periodic points vanish



## Identifying 'ghost rods': periodic points



Poincaré section for $\tau_{f}>1$

- For $\tau_{f}>1$, groups of elliptic and saddle periodic points of period 3
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## Identifying 'ghost rods': periodic points



- Periodic points of period $3 \Rightarrow$ act as 'ghost rods'
- Their braid has $h_{\mathrm{TN}}=0.96242$ from TNCT
- Actual $h_{\text {flow }} \approx 0.964$
- $\Rightarrow h_{\mathrm{TN}}$ is an excellent lower bound



## Topological entropy continuity across critical point

$\square$ Consider $\tau_{f}<1$


## Identifying 'ghost rods'?



Poincaré section for $\tau_{f}<1 \Rightarrow$ no obvious structure!

- Note the absence of any elliptical islands
- No periodic orbits of low period were found
- Is the phase space featureless?


## Almost-invariant set (AIS) approach

- Take probabilistic point of view
- Partition phase space into loosely coupled regions

Almost-invariant sets $\approx$ 'leaky' regions with a long residence time ${ }^{2}$


3-body problem phase space is divided into several invariant and almost-invariant sets.

[^0]
## Almost-invariant set (AIS) approach

- Create box partition of phase space $\mathcal{B}=\left\{B_{1}, \ldots B_{q}\right\}$, with $q$ large
- Consider a $q$-by- $q$ transition (Ulam) matrix, $P$, for our dynamical system, where

$$
P_{i j}=\frac{m\left(B_{i} \cap f^{-1}\left(B_{j}\right)\right)}{m\left(B_{i}\right)}
$$

the transition probability from $B_{i}$ to $B_{j}$ using, e.g., $f=\phi_{t}^{t+T}$


- $P$ approximates our dynamical system via a finite state Markov chain.


## Almost-invariant set (AIS) approach

- A set $B$ is called almost invariant over the interval $[t, t+T]$ if

$$
\rho(B)=\frac{m\left(B \cap \phi^{-1}(B)\right)}{m(B)} \approx 1
$$

- Can maximize value of $\rho$ over all possible combinations of sets $B \in \mathcal{B}$.
- In practice, AIS or relatedly, almost-cyclic sets (ACS), identified via eigenvectors (of eigenvalues with $|\lambda| \approx 1$ ) of $P$ or graph-partitioning
- Appropriate for non-autonomous, aperiodic, finite-time settings


## Identifying 'ghost rods': almost-cyclic sets



- Return to $\tau_{f}>1$ case, where periodic points and manifolds exist
- Agreement between AIS boundaries and manifolds of periodic points
- Known previously ${ }^{3}$ and applies to more general objects than periodic points, i.e. normally hyperbolic invariant manifolds (NHIMs)

[^1]
## Identifying 'ghost rods': almost-cyclic sets



- Return to $\tau_{f}>1$ case, where periodic points and manifolds exist
- Agreement between AIS boundaries and manifolds of periodic points
- Known previously ${ }^{4}$ and applies to more general objects than periodic points, i.e. normally hyperbolic invariant manifolds (NHIMs)

[^2]
## Identifying 'ghost rods': almost-cyclic sets



Poincaré section for $\tau_{f}<1 \Rightarrow$ no obvious structure!

- Return to $\tau_{f}<1$ case, where no periodic orbits of low period known
- Is the phase space featureless?
- Consider transition matrix $P_{t}^{t+\tau_{f}}$ induced by Poincaré map $\phi_{t}^{t+\tau_{f}}$


## Identifying 'ghost rods': almost-cyclic sets

Top eigenvectors for $\tau_{f}=0.99$ reveal hierarchy of phase space structures


$\nu_{3}$

$\nu_{5}$

$\nu_{6}$

## Identifying 'ghost rods': almost-cyclic sets



The zero contour (black) is the boundary between the two almost-invariant sets.

- Three-component AIS made of 3 almost-cyclic sets (ACSs) of period 3
- ACS effectively replace compact region bounded by saddle manifolds
- Also: we see a dynamical remnant of the global 'stable and unstable manifolds' of the saddle points, despite no saddle points


## Identifying 'ghost rods': almost-cyclic sets

Almost-cyclic sets stirring the surrounding fluid like 'ghost rods'

- works even when periodic orbits are absent!

Movie shown is second eigenvector for $P_{t}^{t+\tau_{f}}$ for $t \in\left[0, \tau_{f}\right)$

## Identifying 'ghost rods': almost-cyclic sets



Braid of ACSs gives lower bound of entropy via Thurston-Nielsen - One only needs approximately cyclic blobs of fluid

- Even though the theorems require exactly periodic points!
- Stremler, Ross, Grover, Kumar [2011] Phys. Rev. Lett.


## Topological entropy vs. bifurcation parameter



- $h_{\mathrm{TN}}$ shown for ACS braid on 3 strands


## Eigenvalues/eigenvectors vs. bifurcation parameter



Movie shows change in eigenvector along branch marked with '_ם-' above (a to f),
as $\tau_{f}$ decreases $\Rightarrow$

## Bifurcation of ACSs

For example, braid on 13 strands for $\tau_{f}=0.92$
Movie shown is second eigenvector for $P_{t}^{t+\tau_{f}}$ for $t \in\left[0, \tau_{f}\right)$
Thurson-Nielsen for this braid provides lower bound on topological entropy

## Sequence of ACS braids bounds entropy



For various braids of ACSs, the calculated entropy is given, bounding from below the true topological entropy over the range where the braid exists

## Chaotic transport: aperiodic, finite-time setting

- Data-driven, finite-time, aperiodic setting - e.g., non-autonomous ODEs for fluid flow
- How do we get at transport?
- Recall the flow, $x \mapsto \phi_{t}^{t+T}(x)$, where $\phi: \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$



## Identify regions of high sensitivity of initial conditions

- Small initial perturbations $\delta x(t)$ grow like

$$
\begin{aligned}
\delta x(t+T) & =\phi_{t}^{t+T}(x+\delta x(t))-\phi_{t}^{t+T}(x) \\
& =\frac{d \phi_{t}^{t+T}(x)}{d x} \delta x(t)+O\left(\|\delta x(t)\|^{2}\right)
\end{aligned}
$$



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\end{aligned}
$$



## Invariant manifold analogs: FTLE-LCS approach

- The finite-time Lyapunov exponent (FTLE),

$$
\sigma_{t}^{T}(x)=\frac{1}{|T|} \log \left\|\frac{d \phi_{t}^{t+T}(x)}{d x}\right\|
$$

measures the maximum stretching rate over the interval $T$ of trajectories starting near the point $x$ at time $t$

- Ridges of $\sigma_{t}^{T}$ are candidate hyperbolic codim-1 surfaces; finite-time analogs of stable/unstable manifolds; 'Lagrangian coherent structures'5




[^3]
## Invariant manifold analogs: FTLE-LCS approach



Autonomous double-gyre flow

## Invariant manifold analogs: FTLE-LCS approach



## Invariant manifold analogs: FTLE-LCS approach



Invariant manifolds


LCS

Time-periodic oscillating vortex pair flow

## Invariant manifold analogs: FTLE-LCS approach

- We can define the FTLE for Riemannian manifolds ${ }^{3}$

$$
\sigma_{t}^{T}(x)=\frac{1}{|T|} \ln \left\|\mathrm{D} \phi_{t}^{t+T}\right\| \doteq \frac{1}{|T|} \log \left(\max _{\mathrm{y} \neq 0} \frac{\left\|\mathrm{D} \phi_{t}^{t+T}(\mathrm{y})\right\|}{\|\mathrm{y}\|}\right)
$$

with y a small perturbation in the tangent space at $x$.


## Transport barriers on Riemannian manifolds

- Ridges correspond to dynamical barriers ${ }^{3}$ or Lagrangian coherent structures (LCS): repelling surfaces for $T>0$, attracting for $T<0$

cylinder

Moebius strip
Each frame has a different initial time $t$

[^4]
## Atmospheric flows: Antarctic polar vortex

## Atmospheric flows: Antarctic polar vortex

ozone data + LCSs (red $=$ repelling, blue $=$ attracting )

## Atmospheric flows: Antarctic polar vortex

air masses on either side of a repelling LCS

## Atmospheric flows: continental U.S.

LCSs: orange $=$ repelling, blue $=$ attracting

## Atmospheric flows and lobe dynamics


orange $=$ repelling LCSs , blue $=$ attracting LCS
satellite

Andrea, first storm of 2007 hurricane season
cf. Sapsis \& Haller [2009], Du Toit \& Marsden [2010], Lekien \& Ross [2010], Ross \& Tallapragada [2011]

## Atmospheric flows and lobe dynamics



Andrea at one snapshot; LCS shown (orange $=$ repelling, blue $=$ attracting)

## Atmospheric flows and lobe dynamics


orange $=$ repelling (stable manifold),$\quad$ blue $=$ attracting (unstable manifold)

## Atmospheric flows and lobe dynamics


orange $=$ repelling (stable manifold),$\quad$ blue $=$ attracting (unstable manifold)

## Atmospheric flows and lobe dynamics



Portions of lobes colored; magenta $=$ outgoing, green $=$ incoming, purple $=$ stays out

## Atmospheric flows and lobe dynamics



Portions of lobes colored; magenta $=$ outgoing, green $=$ incoming, purple $=$ stays out

## Atmospheric flows and lobe dynamics

Sets behave as lobe dynamics dictates

## Atmospheric transport network relevant for aeroecology

Skeleton of large-scale horizontal transport
relevant for large-scale
spatiotemporal patterns
of important biota
e.g., plant pathogens

## 2D curtain-like structures bounding air masses

## 2D curtain-like structures bounding air masses



## Pathogen transport: filament bounded by LCS


(a)

(b)

(c)


## Pathogen transport: filament bounded by LCS


(a)

(d)

(b)

(e)

15:00 UTC 1 May 2007

(c)

(f)

18:00 UTC 1 May 2007

## Coherent sets and set-based definition of FTLE

- Consider, e.g., a flow $\phi_{t}^{t+T}$ in $\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}$.
- Treat the evolution of set $B \subset \mathbb{R}^{2}$ as evolution of two random variables $X_{1}$ and $X_{2}$ defined by probability density function $f\left(x_{1}, x_{2}\right)$, initially uniform on $B, f=\frac{1}{\mu(B)} \mathcal{X}_{B}$, with $\mathcal{X}_{B}$ the characteristic function of $B$.
- Under the action of the flow $\phi_{t}^{t+T}, f$ is mapped to $P f$ where $P$ is the associated Perron-Frobenius operator.
- Let $I(f)$ be the covariance of $f$ and $I(P f)$ the covariance of $P f$.


Deformation of a disk under the flow during $[t, t+T]$

## Coherent sets and set-based definition of FTLE

- Definition. The covariance-based FTLE of $B$ is

$$
\sigma_{I}(B, t, T)=\frac{1}{|T|} \log \left(\frac{\sqrt{\lambda_{\max }(I(P f))}}{\sqrt{\lambda_{\max }(I(f))}}\right)
$$

- Reduces to usual definition of FTLE in the limit that the linearization approximation (i.e., line-stretching method) is valid


Deformation of a disk under the flow during $[t, t+T]$

## Coherent sets and set-based definition of FTLE

- The coherence of a set $B$ during $[t, t+T]$ is $\sigma_{I}(B, t, T)$.
- A set $B$ is almost-coherent during $[t, t+T]$ if $\sigma_{I}(B, t, T) \approx 0$.
- Captures the essential feature of a coherent set: it does not mix or spread significantly in the domain.
- This definition also can identify non-mixing translating sets.



## Coherent sets and set-based definition of FTLE

- The coherence of a set $B$ during $[t, t+T]$ is $\sigma_{I}(B, t, T)$.
- A set $B$ is almost-coherent during $[t, t+T]$ if $\sigma_{I}(B, t, T) \approx 0$.
- Captures the essential feature of a coherent set: it does not mix or spread significantly in the domain.
- This definition also can identify non-mixing translating sets.
- Values of $\sigma_{I}(B, t, T)$ determine the family of sets of various degrees of coherence.
- Need to set a heuristic threshold on the value of $\sigma_{I}(B, t, T)$ to determine coherent sets.
- Notice, coherent sets will be separated by ridges of high FTLE, i.e., LCS


## Coherent sets in lid-driven cavity flow



FTLE from line-stretching (conventional) during $\left[0, \tau_{f}\right]$

## Coherent sets in lid-driven cavity flow



FTLE from covariance-based approach during $\left[0, \tau_{f}\right]$

## Coherent sets in lid-driven cavity flow



Sets of coherences $\sigma_{I}\left(0, \tau_{f}\right)<0.06$

## Coherent sets in lid-driven cavity flow



Compare coherent set with AIS from second eigenvector of $P$

## Coherent sets in lid-driven cavity flow



Compare coherent sets with non-coherent set (gray)

## Coherent sets in lid-driven cavity flow

1


## Coherent sets in the atmosphere



## Coherent sets in the atmosphere



- FTLE from covariance during 24 hours starting 09:00 1 May 2007


## Coherent sets in the atmosphere



- Coherent sets during 24 hours starting 09:00 1 May 2007


## Optimal navigation in an aperiodic setting?

- Selectively 'jumping' between coherent air masses using control
- Moving between mobile subregions of different finite-time itineraries



## Optimal navigation in an aperiodic setting?

- Selectively 'jumping' between coherent air masses using control
- Moving between mobile subregions of different finite-time itineraries


## Chaotic transport in higher dimensional systems

$\square$ e.g., Hamiltonian systems with multiple potential wells.
$\square$ What structures guide transport between potential wells?

- e.g., restricted three-body problem

$$
H=\frac{1}{2}\left(\left(p_{x}+y\right)^{2}+\left(p_{y}-x\right)^{2}\right)+\bar{U}(x, y),
$$

where

$$
\bar{U}(x, y)=-\frac{1}{2}\left(x^{2}+y^{2}\right)-\frac{1-\mu}{r_{1}}-\frac{\mu}{r_{2}}
$$



## Motion in energy surface

$\square$ Energy surface of energy $E$ is codim-1 surface

$$
\mathcal{M}(E)=\{(\mathrm{q}, \mathrm{p}) \mid H(\mathrm{q}, \mathrm{p})=E\} .
$$

$\square$ e.g., in 2 d.o.f., 3D surfaces foliating 4D phase space

## Realms of possible motion


$\square \mathcal{M}(E)$ partitioned into three realms e.g., Earth realm $=$ phase space around Earth
$\square$ Energy $E$ determines their connectivity

## Realms of possible motion



Case 1:E<E1


Case 2 : $E_{1}<E<E_{2}$


Case 3: $E_{2}<E<E_{3}$


Case 4 : $E_{3}<E<E_{4}$


Case $5: E>E_{4}$

## Motion near saddles

$\square$ Near rank 1 saddles in $N$ degree of freedom system, linearized vector field eigenvalues are

$$
\pm \lambda \text { and } \pm i \omega_{j}, j=2, \ldots, N
$$

$\square$ Under local change of coordinates

$$
H(q, p)=\lambda q_{1} p_{1}+\sum_{i=2}^{N} \frac{\omega_{i}}{2}\left(p_{i}^{2}+q_{i}^{2}\right)
$$

to lowest order

## Motion near saddles

$\square$ Equilibrium point is of type saddle $\times$ center $\times \cdots \times$ center ( $N-1$ centers)

the $N$ canonical planes

## Motion near saddles

$\square$ For energy $h$ just above saddle pt, $\left(q_{1}, p_{1}\right)=(0,0)$ is normally hyperbolic invariant manifold of bound orbits

$$
\mathcal{M}_{h}=\sum_{i=2}^{N} \frac{\omega_{i}}{2}\left(p_{i}^{2}+q_{i}^{2}\right)=h>0
$$




the $N$ canonical planes

## Motion near saddles

$\square$ Note that $\mathcal{M}_{h} \simeq S^{2 N-3}$

- $N=2$, the circle $S^{1}$, a single periodic orbit
- $N=3$, the 3 -sphere $S^{3}$, a set of periodic and quasi-periodic orbits

the $N$ canonical planes


## Motion near saddles

$\square$ Note that $\mathcal{M}_{h} \simeq S^{2 N-3}$

- $N=2$, the circle $S^{1}$, a single periodic orbit
- $N=3$, the 3 -sphere $S^{3}$, a set of periodic and quasi-periodic orbits
$\square$ Four "cylinders" or tubes of asymptotic orbits: stable, unstable manifolds, $W_{ \pm}^{s}\left(\mathcal{M}_{h}\right), W_{ \pm}^{u}\left(\mathcal{M}_{h}\right), \simeq S^{1} \times \mathbb{R}$ for $N=2$



## Motion near saddles: 2 d.o.f.

- B : bounded orbits (periodic/quasi-periodic): $S^{1}$
- A : asymptotic orbits to 1 -sphere: $S^{1} \times \mathbb{R}$ (tubes)
- T : transit and NT : non-transit orbits.



## Tube dynamics: inter-realm transport



- Tube dynamics: All motion between adjacent realms connected by necks around saddles must occur through the interior of tubes ${ }^{6}$

${ }^{6}$ Koon, Lo, Marsden, Ross [2000,2001,2002], Gómez, Koon, Lo, Marsden, Masdemont, Ross [2004]

## Related systems

- Much work in celestial mechanics
- Results apply to problems in chemistry, biomechanics, ship capsize



## Tubes leading to capsize

- Ship motion is Hamiltonian,

$$
H=p_{x}^{2} / 2+R^{2} p_{y}^{2} / 4+V(x, y)
$$



## Tubes leading to capsize



## Tubes leading to capsize

- Wedge of trajectories leading to imminent capsize

- Tubes are a useful paradigm for predicting capsize even in the presence of random forcing, e.g., random waves
- Could inform control schemes to avoid capsize in rough seas


## Final words on chaotic transport

$\square$ What are robust descriptions of transport which work in data-driven aperiodic, finite-time settings?

- Possibilities: finite-time lobe dynamics / symbolic dynamics may work - finite-time analogs of homoclinic and heteroclinic tangles
- Probabilistic, geometric, and topological methods
— invariant sets, almost-invariant sets, almost-cyclic sets, coherent sets, stable and unstable manifolds, Thurston-Nielsen classification, FTLE, LCS
- Many links between these notions - e.g., LCS locate analogs of stable and unstable manifolds
- boundaries between coherent sets are naturally LCS
- periodic points $\Rightarrow$ almost-cyclic sets
— their 'stable/unstable invariant manifolds' $\Rightarrow$ ???


## The End

## For papers, movies, etc., visit: www.shaneross.com

## Main Papers:

- Stremler, Ross, Grover, Kumar [2011] Topological chaos and periodic braiding of almost-cyclic sets. Physical Review Letters 106, 114101.
- Tallapragada, Ross, Schmale [2011] Lagrangian coherent structures are associated with fluctuations in airborne microbial populations. Chaos 21, 033122.
- Lekien \& Ross [2010] The computation of finite-time Lyapunov exponents on unstructured meshes and for non-Euclidean manifolds. Chaos 20, 017505.
- Senatore \& Ross [2011] Detection and characterization of transport barriers in complex flows via ridge extraction of the finite time Lyapunov exponent field, International Journal for Numerical Methods in Engineering 86, 1163.
- Grover, Ross, Stremler, Kumar [2011] Topological chaos, braiding and breakup of almost-invariant sets. Preprint.
- Tallapragada \& Ross [2011] A geometric and probabilistic description of coherent sets. Preprint.


[^0]:    ${ }^{2}$ Dellnitz, Junge, Koon, Lekien, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Int. J. Bif. Chaos

[^1]:    ${ }^{3}$ Dellnitz, Junge, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Phys. Rev. Lett.; Dellnitz, Junge, Koon, Lekien, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Int. J. Bif. Chaos

[^2]:    ${ }^{4}$ Dellnitz, Junge, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Phys. Rev. Lett.; Dellnitz, Junge, Koon, Lekien, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Int. J. Bif. Chaos

[^3]:    ${ }^{5}$ cf. Bowman, 1999; Haller \& Yuan, 2000; Haller, 2001; Shadden, Lekien, Marsden, 2005

[^4]:    ${ }^{3}$ Lekien \& Ross [2010] Chaos

